Steering Task-List

Software:

-Write rotate class and integrate with ROS using True and Mod Tick method ...Done

-Fix RC values around 0 for Elev and Thro

-Test rotate class

-Test velocity class

-Integrate all classes and test with 4 RoboClaws

-Inititialization for wheels using magnetic proximity sensor

-Script for ACM0, ACM1 ...

-fit-pc update firmware for ROS and Linux

Hardware:

-Battery source for RoboClaw

-Make wiring of Arduino for RC Stick permanent

-Test connections of RoboClaw with motor for correct direction of rotation